

Automation & Digitalization in the Cranes Industry

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Agenda

1

Modular Automation

Remote Operate Control System Load Collision Prevention Truck Positioning System

2

Trimodal Equipment Logistics System

Stack management Rail management Gate management Dangerous goods Open platform

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Presenter Gerhard Fischer



1983-1987 University Applied Science Munich
1988 Arizona State University, Tempe AZ
1989 German Military
1990 –1995 Siemens AG R&D
1995 –1998 Siemens Pte. Ltd. Singapore
1998 –2002 Siemens Ltd. Taiwan
2002 –2004 Siemens AG Germany
2004 –2008 Siemens Netherlands
2008 – Siemens AG Germany

Memberships:

VDI AK304 "cranes" DKE for IEC 60204-32 PEMA ED&I vice chair IEEE industry applications society



Evergreen Kaohsiung – 19 STS and 56 ARMG Full automation and digital twinning of the terminal

Project information	 Integrated automation, drive and control systems for 67 cranes Engineering, integration and optimization 22 ARMG + 6 STS by June 2022 18 ARMG + 5 STS by June 2023 16 ARMG + 8 STS by Jan 2024
Customer challenge	 High level of automation and digitalization Integration to in-house TOS "Future proofing" via modular and open concept Commissioning under Covid-19 impact (virtual commissioning)
Siemens solution	 Digital twinning in every aspect/phase of the project Remote Control Operating System and Remote Control Training Simulator Siemens Equipment Logistic System with TOS integration Simocrane modules: ARMG: RCOS, LCPS, FLS, SPMS, TPS, CLPS STS: RCOS, Sway Control, Vessel Profile Scanning, SPMS, TPS
Customer benefits	 State of the art automation technology Optimal equipment utilization Maximized availability







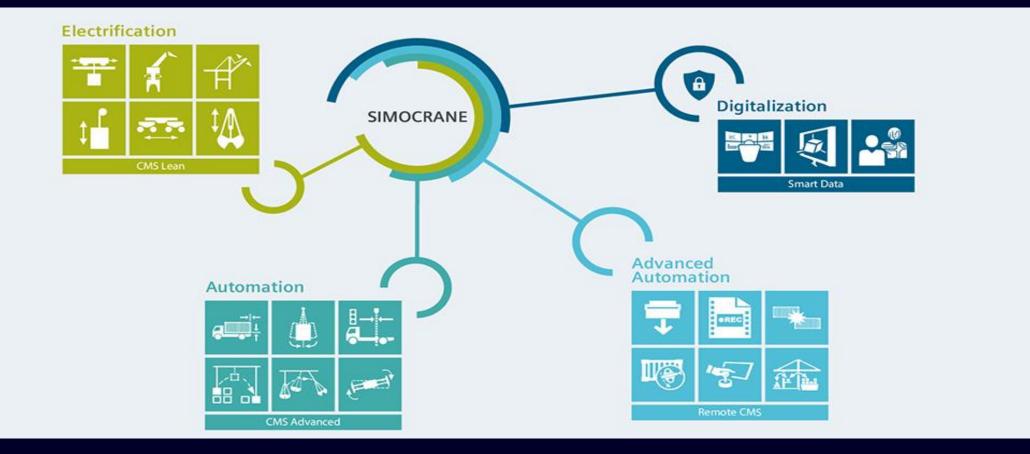
Patrick Sydney 3 ARMG

Project information	 3 ARMG Linking the container yard to the rail interface Straddle carriers as horizontal transport
Customer	Automatic rail car handling
challenge	Personnel safety
Siemens	 Extensive use of digital twin & simulation
Siemens solution	Extensive use of digital twin & simulationCranes for train scan
	Cranes for train scan
	 Cranes for train scan Simocrane modules RCOS, LCPS, FLS, OCR,
solution Customer	 Cranes for train scan Simocrane modules RCOS, LCPS, FLS, OCR,
solution	 Cranes for train scan Simocrane modules RCOS, LCPS, FLS, OCR, CMS/RCMS, strad positioning





Modular Automation SIMOCRANE Trends Fully Modular Automation Solution for Terminals

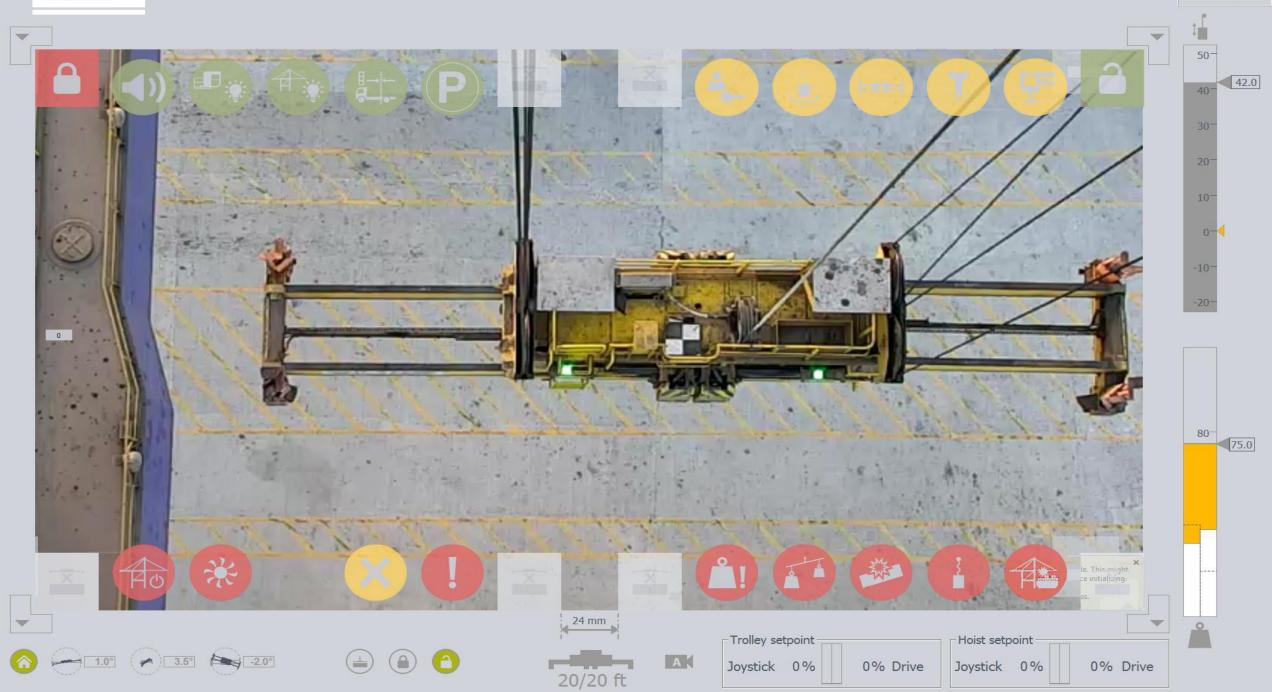




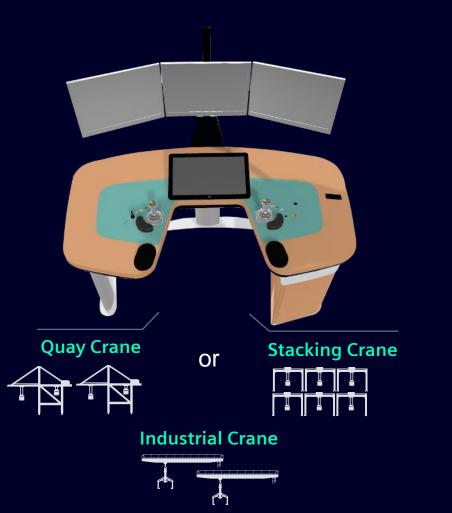
Simocrane RCOS Remote Control Operating System



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Simocrane RCOS Functionality





"Any to any" operator connects to any crane from any desk.



"Pooling" connects crane to a free desk when assistance is needed



"Decentral Concept"

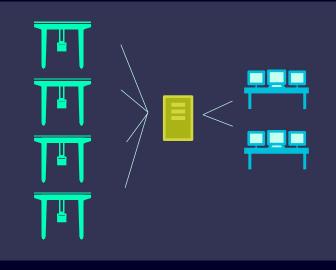
- Decentral PLC softwareRedundant Server Pair
- No single point of failure

"Integration & Interfacing"

can be applied to non-Siemens PLC's, offers interfacing with TOS

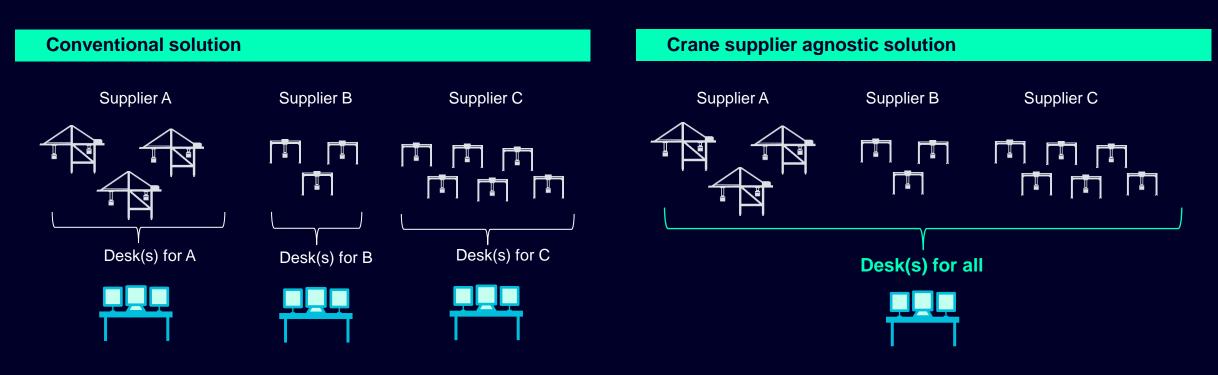








Agnostic Remote Control



- End-user accepted proprietory solutions from different crane suppliers
- Desks of one supplier can only control cranes by this supplier
- No any-to-any possible
- No pooling of remote drives for whole fleet
- Multiple maintenance effort
- Higher complexity cybersecurity protection

• End-user specified to different crane builder Simocrane RCOS module

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- Any crane is controllable from any desk
- Pooling of remote drives for whole fleet
- Single system to be maintanied
- · Best situation for cybersecurity protection



Laser Sensor System TPS - Truck Positioning System

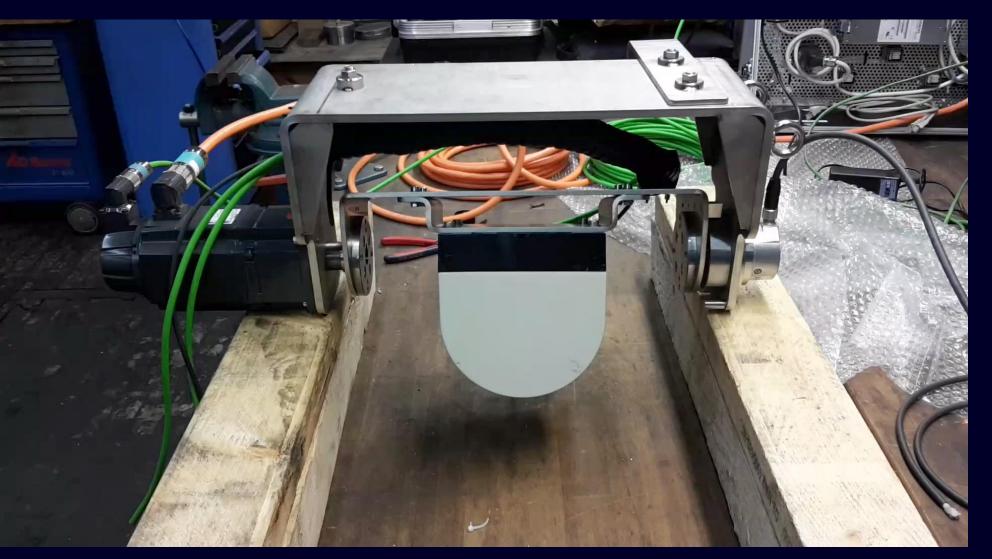
Precise laser measurement system for accurate truck positioning

Laser measuring system provides position data from parameterized objects, trucks, trailers and containers.





Siemens 3D Laser Scanner Swivel Unit



Performance

• +15% crane performance

Technical info

Gearless SIEMENS
 drive

(Sinamics, 1FT6 servo)

- Double encoders option
- Encoder synchronized
 laser data
- Up to 40 degree/sec scan speed (from 5 deg/sec)

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Laser Sensor System TPS - Truck Positioning System

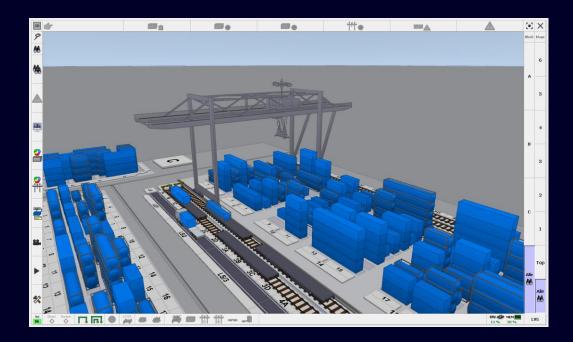
Cabin position monitoring with 3D laser measurement





Stack management

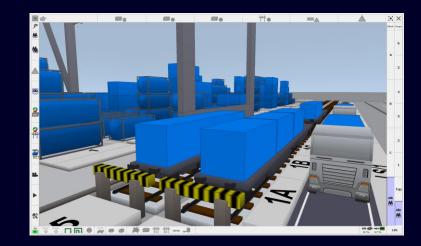
- ISO and tank containers, trailers
- Stack management bay-row-tier and mm-coordinates
- Location finding, based on
 - Container type and stacking rules
 - Weight
 - Physical restrictions
 - Expected time of departure (truck, train)
 - DGR-rules
- Housekeeping
- Automatic and/or manual activation of movements
- Inventory check functions





Rail track management

- Interface to commercial terminal management system / rail operator
- Train pre-announcement
- Verification after train arrival
- Inventory of wagons and containers
- Location based on sections or mm-coordinates
- Verification via OCR-interface
- Scheduling train loading, time supervision







Gate interface, truck management

- Gate dialog functions or interface to gate system (to register trucks)
- Assign position for truck (loading lane / parking area)
- Call trucks from the parking area
- Align with crane operator in case of manual movement activation





Dangerous goods

- Managing contents for DGR containers
- Mapping of contents into categories
- Rule sets for each category
 - Time rules
 - Distance rules
 - Quantity rules
 - Combination of these attributes
- Integrated in 3D visualization
- Mapping of national rules into categories
 => international solution

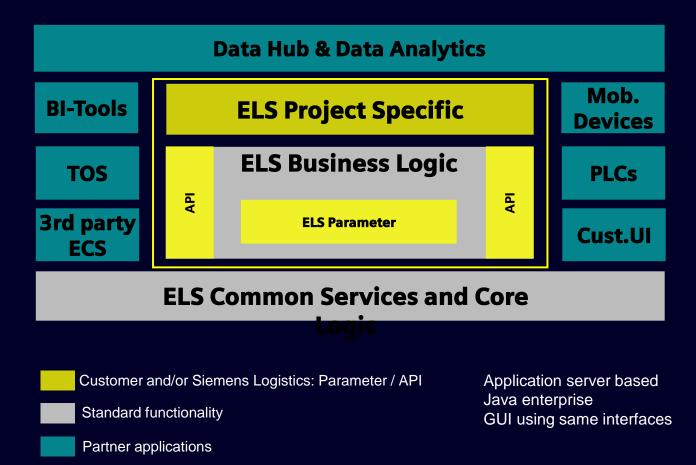




ELS – Platform Architecture

Open Architecture

- Stable core functionality
- Business logic configured by parameters
- Open API, i.e. to TOS, PLCs, HT, BI, Data Warehouse, ...
- APIs can be used by other ECS or customer UI
- Project specific part planned to be fully open

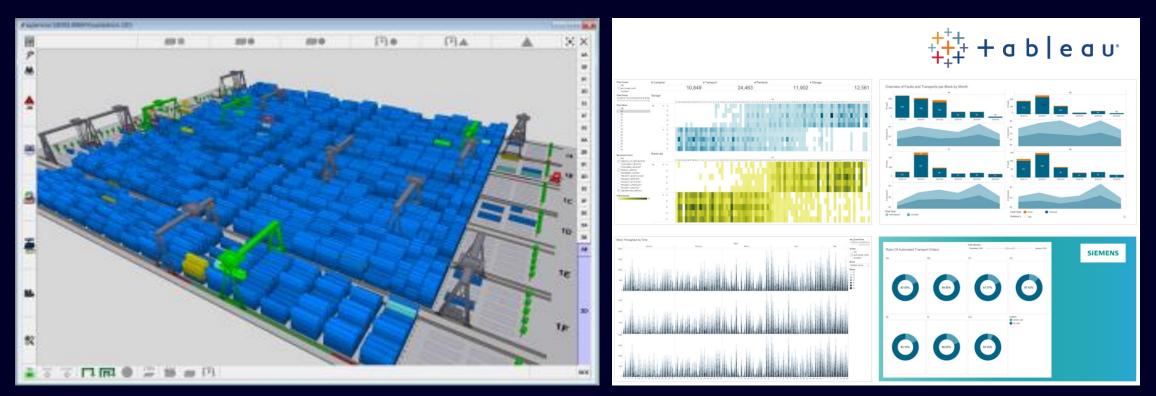




Data Warehouse and Data Analytics

Derivation key KPI

e.g. crane, block, transfer zone utilization





Equipment Logistics System Example Brownfield Integration of a Block

Typical setup in a brownfield terminal

- Existing TOS, i.e. Navis, Cyberlogitec, Tideworks,
- Existing PLC-System for equipment, Siemens Simatic S7 or 3rd party PLCs
- Existing middleware as interface exchanger with less/ no logistical logic

Integration in a brownfield terminal

- Standard interfaces (APIs) to TOS and PLC
- Option: Interface transformer if required
- Individual transformers to connect existing environment to ELS

